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Volume 3077

**Proceedings of the Transdisciplinary  
Symposium on Engineering and  
Technology (TSET) 2022  
Development of Digital and Green  
Technology on Post Pandemic Era**

Yogyakarta, Indonesia • 21 September 2022

**Editors • Ade Gafar Abdullah, Desi Ramayanti, Henri Septanto  
and Yohanes Galih Adhiyoga**



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RESEARCH ARTICLE | JULY 12 2024

# SCADA application for popcorn cooking and packaging system using PLC and internet

Theresia Prima Ari Setiyani ; Geraldine Valda Prakusya Putri Ayu; Ignatia Diva Saniscara



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# SCADA Application for Popcorn Cooking and Packaging System Using PLC and Internet

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**Abstract.** The modern food industry requires real-time remote automation and monitoring processes. This paper develops automation for popcorn processing to packaging that can be monitored via the internet. The system is designed to monitor the temperature, quality of the popcorn and its packaging. The system is designed to be able to detect any anomalies in the process and alert operators via email or text message. The prototype consists of 2 containers of raw corn with 2 flavors, a cooking pot and its heating element, and a conveyor. Each container is equipped with a rotary vane feeder that can be adjusted the number of rotations to determine the volume of raw corn that is poured with certain variants into the cooking pan as desired by the user through the HMI. Detection of packaging position, rotary vane feeder, volume, and temperature carried out by a photodiode and thermocouple. Control system using PLC TM221CE40R which has an analog module and ethernet port. The result that system was able to cook and package 4 types of products, monitors the process that occurs in the plan remotely in real-time, and stores the daily number of products.

## INTRODUCTION

Popcorn is a kind of snack that is not fried, nutritious, healthy, crunchy, savory, available in various flavors, so it is one of the most favorite recreational snacks for children as well as adults [1]. This corn kernel-based dish is usually prepared by heating it in a kettle over medium heat [2]. The home popcorn industry in Indonesia is growing quite rapidly because it only requires a small amount of capital, but the profit is good. The use of manual equipment in making popcorn takes a long time, the lack of guarantees for the cleanliness of the product and process monitoring must be carried out continuously [3-4]. Because of this, the popcorn industry requires the support of automatic popcorn machines that are used to simplify the production and control process.

Dong has conducted research on the application of mechanical automation for automatic control form of food packaging machinery, application of drive and sensor technology, and application of automatic identification technology. In order to better improve and give it better food packaging efficiency, the introduction of a complete monitoring system is good to achieve effective supervision of the operation of various packaging machinery and equipment end using intelligent technology [5].

SCADA (Supervisory Control and Data Acquisition) is an automation system that can supervise, control and acquire data on a plant. Data acquisition is carried out on electrical signals from sensors and other measuring instruments to be processed into actions according to the desired program. With SCADA users can monitor and control an industrial device remotely using certain software and transfer data in real-time. The controller components in SCADA usually use PLC (Programmable Logic Controllers) [6,7]. PLC have become the main controller of industrial equipment, such as modern packaging automation systems. Strong reasons have favored this trend, instead of using

custom made controller systems: using a standard hardware assures rapid prototyping, quality parts at a reasonable cost, specialized maintenance support, availability of skilled programmers, and incremental upgrading to more powerful hardware that can increase the machine performance or add new capabilities such as internet connection, database logging of production data, or even flexible lines to follow closely changing production demands [8].

The growth of the Internet of Things (IoT) in the food industry offers many new paradigm shifts, mainly related to equipment automation management and production process supervision. IoT allows the system to be centralized in controlling, managing big data and monitoring all production processes remotely. This condition answers the companies need to monitor the progress of their production in real time via the internet. In the era of IoT technology, SCADA data can be routed via Ethernet or TCP/IP networks, thus enabling remote monitoring [9-10]. The construction of a Supervisory Control and Data Acquisition system (SCADA) and the corresponding Human-Machine Interface (HMI) for desalination plant using the MPI connection in main control loop instead of Ethernet connection the most important benefit from using SCADA system is decreasing the operation time [11].

Monitoring and controlling heating process using PLC and SCADA has been done. SCADA is used for the purpose to see the view of the full machine, display alarms, trends, reporting of the furnace in SQL server. By using this technique, it can be analyzed in terms of monitoring, controlling the furnace, efficiency, avoiding waste energy, accuracy, fault history industrial production and performance of the whole system [12]. There have been many implementations of SCADA for other fields, including for oil storage [7], desalination [11], dairy industry [13], floating docks [14], liquid and detergent factory [15], etc.

Based on this, a SCADA application will be developed for a prototype popcorn processing machine from raw corn to packaged popcorn. The system consists of the control section and the supervision section. Control is carried out on the sensor and actuator devices owned by the machine. The controller uses a Schneider TM221CE40R PLC because it has an ethernet port and an analog module. Supervision of the production process on the machine is carried out through HMI. Communication between PLC and HMI is done via ethernet so that monitoring can be done remotely in real-time.

Broadly speaking, the production process starts from the selection of popcorn flavor variants by the user through HMI. There are two flavor variants to choose from, namely sweet and original, as well as 2 volume options, namely small and large. Corn with these flavors are each placed in 2 different containers. Each end of the container has a rotary vane feeder that can be adjusted for the number of turns. When the rotary vane feeder rotates, a number of raw corn will enter the kettle which has been equipped with a heating element. The result of the user's choice will determine which containers rotary vane feeder will rotate and how long it will rotate. The next process is heating raw corn with a certain temperature and for a certain time so that all the corn turn into popcorn. The resulting popcorn will be loaded into empty packages transported by conveyors. The last process is the conveyor will transport the popcorn packaging to the next stage of production. Users can monitor the animation of the entire process that occurs through the HMI screen.

With the SCADA system on the popcorn cooking machine prototype that can be monitored remotely and record the amount of production, it is hoped that the popcorn production process will be more efficient, more practical and product hygiene is maintained.

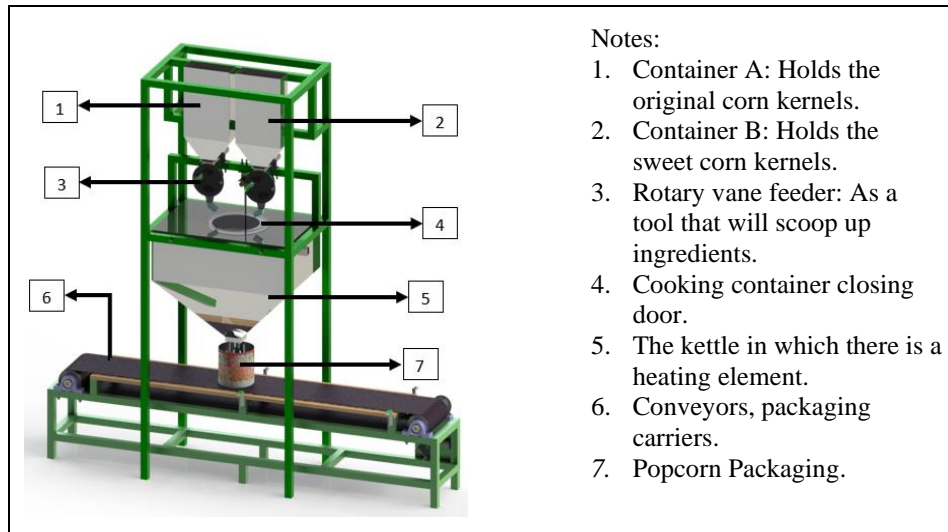
## METHODS

### Popcorn Cooking Machine Prototype Design

The popcorn cooker prototype is designed to be able to cook corn into popcorn with a choice of 2 flavors and different packaging sizes. The full design can be seen in Fig. 1.

To control the popcorn cooker machine is equipped with several kinds of sensors. The photodiode sensor is used to detect the position of the packaging carried by the conveyor, detect the number of rotations of the rotary vane feeder motor, and detect the content of raw corn in the container so that if the raw corn in the container are running low, the system will raise an alarm. Data from the thermocouple temperature sensor is used to stop the heater when it reaches the desired temperature. The DC motor is used to drive the conveyor, rotate the rotary vane feeder, open and close the boiler door.





- Notes:
1. Container A: Holds the original corn kernels.
  2. Container B: Holds the sweet corn kernels.
  3. Rotary vane feeder: As a tool that will scoop up ingredients.
  4. Cooking container closing door.
  5. The kettle in which there is a heating element.
  6. Conveyors, packaging carriers.
  7. Popcorn Packaging.

**FIGURE 1.** Popcorn cooking machine prototype

To control the popcorn cooker machine is equipped with several kinds of sensors. The photodiode sensor is used to detect the position of the packaging carried by the conveyor, detect the number of rotations of the rotary vane feeder motor, and detect the content of raw corn in the container so that if the raw corn in the container are running low, the system will raise an alarm. Data from the thermocouple temperature sensor is used to stop the heater when it reaches the desired temperature. The DC motor is used to drive the conveyor, rotate the rotary vane feeder, open and close the boiler door.

The mechanism for determining the volume of raw corn to be cooked is using a rotary vane feeder which has 2 curves as shown in Fig. 2(a). The rotary vane feeder is placed at the bottom end of container A and container B. The curve on the rotary vane feeder functions like a measuring spoon. For 1 arch is equivalent to  $\pm 35$  grams of raw corn kernels. Each rotary vane feeder is rotated by a DC motor. When the arch is facing up, the arch will be filled with raw corn kernels, while when the arch is facing down, the corn will be poured into the cooking kettle. To calculate the number of rotations of the rotary vane feeder, a photodiode sensor is used.



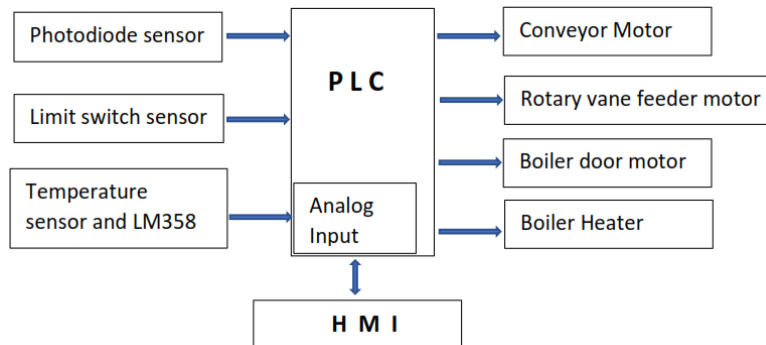
**FIGURE 2.** (a). Rotary vane feeder design with 2 curves and photodiode, (b). The design of a cooking kettle equipped with a thermocouple and heater

The kettle used to cook corn is equipped with a heater that can be adjusted on-off and a thermocouple sensor to determine the temperature of the kettle as can be seen in Fig. 2(b). At the top of the outer housing of the heater there is a closing and opening door that is driven by a DC motor and a pair of limit switches as a door position sensor.

The results of processing in the form of popcorn products will be packaged in a tube-shaped package. The size of the popcorn packaging has a diameter of approximately 10 cm and a height of 15 cm. This package will be filled with popcorn weighing approximately 35-75 gr.

## Block Diagram System Design

The block diagram of the system consists of controlling part carried out by the PLC and the monitoring part carried out by the HMI, as can be seen in Fig.3.



**FIGURE 3.** SCADA block diagram for popcorn cooking and packaging system using PLC and internet

The photodiode sensor is used to detect the position of the packaging carried by the conveyor. If the package is detected under the cooking kettle, the conveyor will stop. The conveyor starts moving again when the popcorn is finished packing. The photodiode sensor is also used to detect the number of rotations of the rotary vane feeder motor, and detect the content of raw corn in containers A and B. If the raw corn in the container are running low, the HMI will raise an alarm so that the operator can immediately fill the raw corn into the container. The limit switch sensor is used to limit the movement of the boiler door during open or close operation. The sensors are connected to the PLC via a digital input port.

The temperature sensor uses a thermocouple. The maximum output voltage of the thermocouple sensor is 11.7 mV with a temperature reaching 316°C. In order to be read clearly by the PLC, the output voltage is amplified using LM358 so that it can reach a voltage of about 8.5 V.

HMI displays a main menu that provides information about options for the user. The REAL-TIME menu displays the options Mode, Composition of flavors and sizes that function to select the popcorn flavor variant and the volume of corn to be produced. This menu also used to start the production process and monitor the ongoing production process. In this display, the user can monitor the temperature value along with the trend and observe whether there is an alarm regarding the volume of raw corn in the container, so that if an alarm appears the user can immediately increase the volume of raw corn in a container that is almost empty. This is necessary so that the popcorn cooking process can take place continuously. Report menu display report and production amount, to see the daily production amount for the last 1 week and save it in the form of a file.

## Internet Communication Design

Data communication between the computer that is used as the HMI and the PLC is done via an ethernet network. In order for the HMI to communicate with the PLC, it is necessary to set up a network configuration which includes the IP address of the PLC and the IP address of the computer used as the HMI. Both must be in the same class. In addition, the Microsoft Windows MBENET application program is used to enable data access on the Modicon PLC via an Ethernet network. The communication protocol will handle data elements in conversations that use a 3-part naming convention, namely Application name, Topic Name, and Item Name.

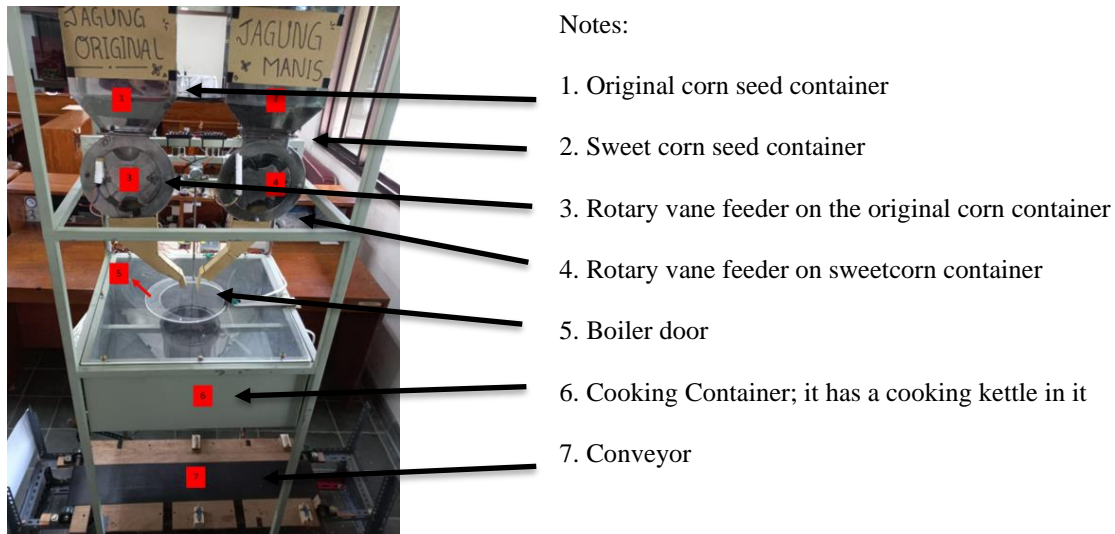
## PLC and HMI Programming

All sensors and actuators are connected to the PLC via digital input ports, digital output ports and analog input modules with a specific addressing format according to the PLC being used. Ladder programming is made using special software that has been provided by the PLC maker. HMI programming is made so that it can display temperature information, temperature trends, input and output equipment conditions and animation of current process. The software used to develop HMI is Wonderware Intouch

## RESULTS AND DISCUSSION

### The Results of the Implementation of the Popcorn Cooker and Packaging Machine Prototype

The physical form of the popcorn cooker and packaging machine has been successfully made like Fig. 4. This tool measures about 75 cm x 50 cm x 175 cm which is separated from the conveyor part. The conveyor is made with a total length of 130 cm while the belt length is 95 cm, height 25 cm and width 26 cm. The conveyor is driven by a DC motor with an input voltage specification of 12V with a rotating speed of 90 rpm and the rotary vane feeder is rotated using a DC motor with a voltage of 24V. The thermocouple temperature range between 125°C - 180°C. This temperature range of the kettle is the optimal temperature so that the corn can turn into popcorn and not burn.



**FIGURE 4.** The results of the implementation of the popcorn cooking and packaging machine prototype

The most likely cause of the discrepancy in speed between the two containers is that there may be a malfunctioning component in either the DC motor or its power supply. If this is true, then it should be checked and replaced if necessary. It is also possible that there are differences in friction between the two containers due to their design or materials used which could affect their speed. In this case, some adjustments may need to be made to ensure that both containers rotate at an equal speed.

To adjust the on-off heater condition so that it corresponds with the temperature range required for optimal popcorn production, a look-up table can be created from Fig. 4 and programmed into the PLC register memory. This will allow for easy adjustment of conditions to achieve the desired temperature range.

### Production Process Observation

Production Process observation is carried out through HMI. The REAL-TIME menu in Fig.5 is used to select the Mode which includes the composition of flavors and sizes, as well as monitoring the condition of the Plant. In the initial condition the indicator lights will be red which it means the system or input output device is still off, the kettle and the kettle cover are white. The packing container will be at the left end of the conveyor.

The operation of this prototype has the following sequence: The user determines the flavor and size variant. There are 4 different flavors and sizes available in HMI, namely Original Small, Original Large, Sweet Small and Sweet Large. The choice of small size will cause the rotary vane feeder in the corn seed container to rotate so that the curve pours 1 spoon of corn into the cooking kettle, while the choice of Large size will cause the rotary vane feeder in the corn seed container to rotate so that the curve pours 2 tablespoons of corn seeds for one production process. After that, choose a production day so that the amount of production that day will be recorded in the report file according to the

selected day. Press the START button to start the cooking and packing process. During the process the user can monitor the cooking and packaging process, temperature values and temperature trends and see whether there are alarms that appear.

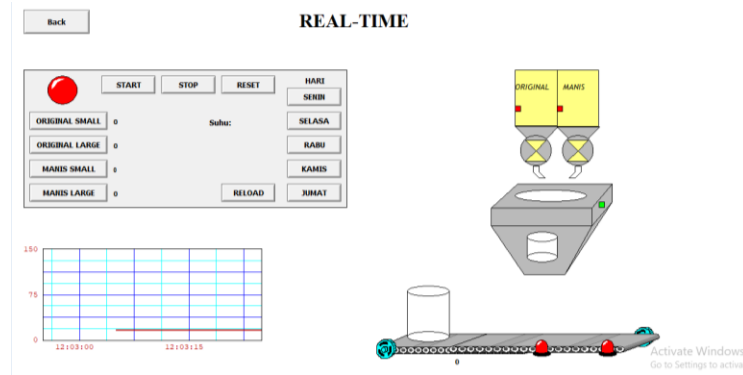


FIGURE 5. REAL-TIME menu display

Many experiments have been carried out to determine the success rate of the prototype with various modes of choice of flavors and sizes provided by HMI. From these observations, it appears that the sequence of processes that occur in the prototype of the popcorn cooking and packaging machine is the same as that shown in the HMI. The sequence of this process has also been in accordance with what was designed. The machine has succeeded in cooking corn into popcorn with flavor and size variant modes according to the user choice. The time needed to process one product is around 12-15 minutes for small size and 15 – 20 minutes for Large size.

However, the construction of the machine that is not quite right means that not all corn can turn into popcorn and not all popcorn goes into the container. This causes the remaining corn and popcorn stay in the heating kettle and get scorched. The machine has achieved a success rate of about 80%.

In order to further improve the success rate, HMI should consider making some modifications to the prototype. The first modification would be to increase the temperature control accuracy and reduce any possible temperature fluctuations. This could help ensure that all corn kernels are heated up evenly for maximum popping efficiency. Additionally, HMI should also look into improving the design of their heating kettle so that it is able to better contain all popcorn within its walls and prevent scorching or burning. Finally, they could add more sensors in order to detect when all of the popcorn has been removed from the kettle and stored in containers before continuing with subsequent processes.

Overall, these modifications can potentially lead to higher rates of success and efficiency in popcorn popping.

## CONCLUSION

SCADA for popcorn cooking and packaging system using PLC and internet has been successfully implemented. The machine is able to cook popcorn with 4 choices of flavor and size variants and then pack it in a package. Improper machine construction causes not all corn can turn into popcorn and not all popcorn goes into the container. This causes the remaining corn and popcorn stay in the heating kettle and get scorched. The cooking and packaging process was successfully monitored through HMI in real time and carried out remotely via the internet. The machine has been tested and all the processes are functioning as expected.

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## Preliminary assessment on the performance of long distance wireless data transmission for disaster early warning system

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## Experimental study a low speed-one phase generator with permanent magnetic radial flux

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## Design and analysis of cabin carbon monoxide warning system

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